

A Brief

# Introduction to SystemVerilog

Instructor: Nima Honarmand

(Slides adapted from Prof. Milder's ESE-507 course)

# First Things First

- Assume you are familiar with the basics of digital logic design
  - If not, you can read Appendix A of Hamacher et al.
- SystemVerilog is a superset of another HDL: Verilog
  - Familiarity with Verilog (or even VHDL) helps a lot
- Useful SystemVerilog resources and tutorials on the course project web page
  - Including a link to a good Verilog tutorial

# Hardware Description Languages

- Used for a variety of purposes in hardware design
  - High-level behavioral modeling
  - Register Transfer Level (RTL) behavioral modeling
  - Gate and transistor level netlists
  - Timing models for timing simulation
  - Design verification and testbench development
  - ...
- Many different features to accommodate all of these
- We focus on RTL modeling for the course project
  - Much simpler than designing with gates
  - Still, helps you think like a hardware designer

# HDLs vs. Programming Languages

- Have syntactically similar constructs:
  - Data types, variables, assignments, if statements, loops, ...
- But very different mentality and semantic model: everything runs in parallel, unless specified otherwise
  - Statement model hardware
  - Hardware is inherently parallel
- Software programs are composed of **subroutines** (mostly)
  - Subroutines **call** each other
  - when in a callee, the caller's execution is paused
- Hardware descriptions are composed of **modules** (mostly)
  - A **hierarchy** of modules **connected** to each other
  - Modules are active at the same time

# Modules

- The basic building block in SystemVerilog
  - Interfaces with outside using **ports**
  - Ports are either **input** or **output** (for now)

all ports declared here

module name

declare which  
ports are inputs,  
which are outputs

```
module mymodule(a, b, c, f);  
    output f;  
    input a, b, c;  
    // Description goes here  
endmodule  
  
// alternatively  
module mymodule(input a, b, c, output f);  
    // Description goes here  
endmodule
```

# Module Instantiation

name of  
module to  
instantiate

```
module mymodule(a, b, c, f);  
    output f;  
    input a, b, c;  
  
    module_name inst_name(port_connections);  
endmodule
```

name of  
instance

connect the ports

- You can instantiate your own modules or pre-defined gates
  - Always inside another module
- Predefined: `and`, `nand`, `or`, `nor`, `xor`, `xnor`
  - for these gates, port order is (output, input(s))
- For your modules, port order is however you defined it

# Connecting Ports (By Order or Name)

- In module instantiation, can specify port connections **by name** or **by order**

```
module mod1(input a, b, output f);  
    // ...  
endmodule  
  
// by order  
module mod2(input c, d, output g);  
    mod1 i0(c, d, g);  
endmodule  
  
// by name  
module mod3(input c, d, output g);  
    mod1 i0(.f(g), .b(d), .a(c));  
endmodule
```

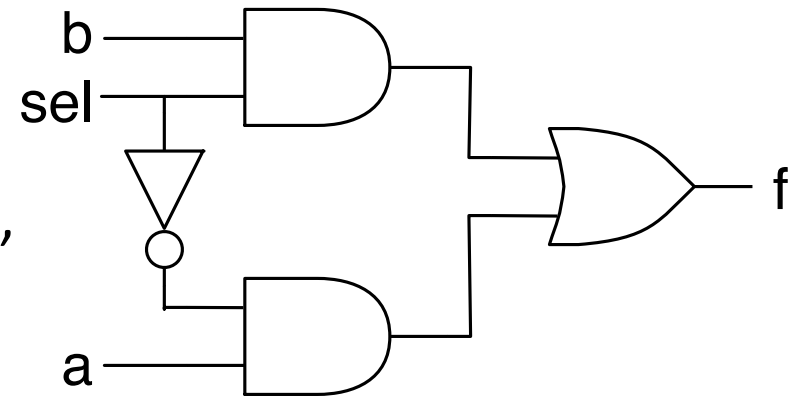
Advice: Use **by-name** connections (where possible)

# Combinational Logic Description



# Structural Design

- Example: multiplexor
  - Output equals an input
  - Which one depends on “sel”



```

module mux(a, b, sel, f);
  output f;
  input a, b, sel;

  logic c, d, not_sel;

  not gate0(not_sel, sel);
  and gate1(c, a, not_sel);
  and gate2(d, b, sel);
  or gate3(f, c, d);
endmodule

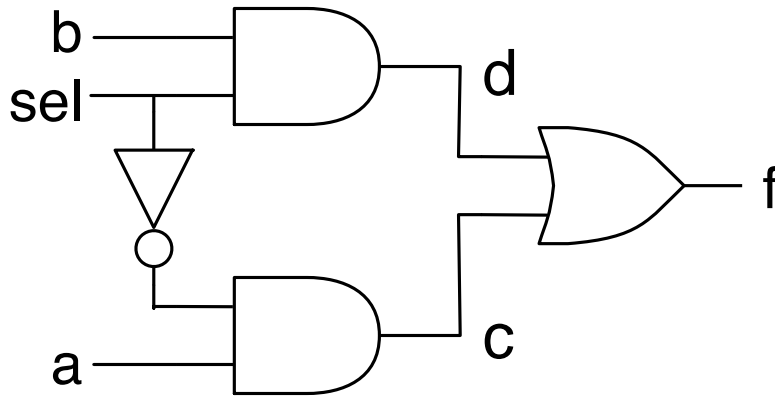
```

datatype for describing logical value

Built-in gates:  
port order is:  
output, input(s)

# Continuous Assignment

- Specify logic *behaviorally* by writing an expression to show how the signals are related to each other.
  - assign statement



```
module mux2(a, b, sel, f);  
    output f;  
    input a, b, sel;  
    logic c, d;  
  
    assign c = a & (~sel);  
    assign d = b & sel;  
    assign f = c | d;  
  
    // or alternatively  
    assign f = sel ? b : a;  
endmodule
```

# Combinational Procedural Block

- Can use `always_comb` procedural block to describe combinational logic using *a series of sequential statements*
- All `always_comb` blocks are independent and parallel to each other

```
module mymodule(a, b, c, f);  
    output f;  
    input a, b, c;  
  
    always_comb begin  
        // Combinational logic  
        // described  
        // in C-like syntax  
    end  
endmodule
```

# Procedural Behavioral Mux Description

```
module mux3(a, b, sel, f);  
    output logic f;  
    input a, b, sel;  
  
    always_comb begin  
        if (sel == 0) begin  
            f = a;  
        end  
        else begin  
            f = b;  
        end  
    end  
end  
endmodule
```

If we are going to drive f this way, need to declare it as logic

Important: for behavior to be combinational, every output (f) must be assigned in all possible control paths

Why? Otherwise, would be a latch and not combinational logic.

# Accidental Latch Description

```
module bad(a, b, f);  
    output logic f;  
    input a, b;  
  
    always_comb begin  
        if (b == 1) begin  
            f = a;  
        end  
    end  
end  
endmodule
```

- This is not combinational, because for certain values of b, f must **remember** its previous value.
- This code describes a latch. (If you want a latch, you should define it using `always_latch`)

# Multiply-Assigned Values

```
module bad2 (...);  
    ...  
    always_comb begin  
        b = ... something ...  
    end  
    always_comb begin  
        b = ... something else ...  
    end  
endmodule
```

- Both of these blocks execute ***concurrently***
- So what is the value of b?  
We don't know!

Don't do this!

# Multi-Bit Values

- Can define inputs, outputs, or logic with multiple bits

```
module mux4(a, b, sel, f);  
    output logic [3:0] f;  
    input [3:0] a, b;  
    input sel;  
  
    always_comb begin  
        if (sel == 0) begin  
            f = a;  
        end  
        else begin  
            f = b;  
        end  
    end  
end  
endmodule
```

# Multi-Bit Constants and Concatenation

- Can give constants with specified number bits
  - In binary or hexadecimal
- Can concatenate with { and }

```
logic [3:0] a, b, c;
logic signed [3:0] d;
logic [7:0] e;
logic [1:0] f;
assign a = 4'b0010; // four bits, specified in binary
assign b = 4'hC; // four bits, specified in hex == 1100
assign c = 3; // == 0011
assign d = -2; // 2's complement == 1110 as bits
assign e = {a, b}; // concatenate == 0010_1100
assign f = a[2 : 1]; // two bits from middle == 01
```



# Case Statements and “Don’t-Cares”

```
module newmod(out, in0, in1, in2);
  input in0, in1, in2;
  output logic out;

  always_comb begin
    case({in0, in1, in2})
      3'b000: out = 1;
      3'b001: out = 0;
      3'b010: out = 0;
      3'b011: out = x;
      3'b10x: out = 1;
      default: out = 0;
    endcase
  end
endmodule
```

output value is  
undefined in this case

Last bit is a “don’t  
care” -- this line will  
be active for 100 OR  
101

default gives “else”  
behavior. Here active  
if 110 or 111

# Arithmetic Operators

- Standard arithmetic operators defined: + - \* / %
- Many subtleties here, so be careful:
  - four bit number + four bit number = five bit number
    - Or just the bottom four bits
  - arbitrary division is difficult

# Addition and Subtraction

- Be wary of overflow!

```
logic [3:0] d, e, f;
assign f = d + e;
```

4'b1000 + 4'b1000 = ...  
In this case, overflows to zero

```
logic [3:0] a, b;
logic [4:0] c;
assign c = a + b;
```

Five bit output can prevent overflow:  
4'b1000 + 4'b1000 gives 5'b10000

- Use “signed” if you want values as 2’s complement

i == 4'b1010 == -6  
j == 5'b11010 == -6

```
logic signed [3:0] g, h, i;
logic signed [4:0] j;
assign g = 4'b0001; // == 1
assign h = 4'b0111; // == 7
assign i = g - h;
assign j = g - h;
```

# Multiplication

- Multiply  $k$  bit number with  $m$  bit number
  - How many bits does the result have?  $k+m$

```
logic signed [3:0] a, b;  
logic signed [7:0] c;  
assign a = 4'b1110; // -2  
assign b = 4'b0111; // 7  
assign c = a*b;
```

$c = 8'b1111\_0010 == -14$

- If you use fewer bits in your code
  - Gets least significant bits of the product

```
logic signed [3:0] a, b, d;  
assign a = 4'b1110; // -2  
assign b = 4'b0111; // 7  
assign d = a*b;
```

$d = 4'0010 == 2$

**Underflow!**

# Sequential Logic Description

# Sequential Design

- Everything so far was purely combinational
  - Stateless
- What about *sequential* systems?
  - flip-flops, registers, finite state machines
- New constructs
  - `always_ff @ (posedge clk, ...)`
  - non-blocking assignment `<=`

# Edge-Triggered Events

- Variant of `always` block called `always_ff`
  - Indicates that block will be sequential logic (flip flops)
- Procedural block occurs only on a signal's edge
  - `@ (posedge ...)` or `@ (negedge ...)`

```
always_ff @(posedge clk, negedge reset_n) begin

    // This procedure will be executed
    // anytime clk goes from 0 to 1
    // or anytime reset_n goes from 1 to 0

end
```

# Flip Flops (1/3)

- q remembers what d was at the last clock edge
  - One bit of memory
- Without reset:

```
module flipflop(d, q, clk);  
    input d, clk;  
    output logic q;  
  
    always_ff @(posedge clk) begin  
        q <= d;  
    end  
endmodule
```



# Flip Flops (2/3)

- Asynchronous reset:

```
module flipflop_asyncr(d, q, clk, rst_n);
  input d, clk, rst_n;
  output logic q;

  always_ff @(posedge clk, negedge rst_n) begin
    if (rst_n == 0)
      q <= 0;
    else
      q <= d;
  end
endmodule
```

# Flip Flops (3/3)

- Synchronous reset:

```
module flipflop_syncr(d, q, clk, rst_n);
    input d, clk, rst_n;
    output logic q;

    always_ff @(posedge clk) begin
        if (rst_n == 0)
            q <= 0;
        else
            q <= d;
    end
endmodule
```

# Multi-Bit Flip Flop

```
module flipflop_asyncr(d, q, clk, rst_n);
    input [15:0] d;
    input clk, rst_n;
    output logic [15:0] q;

    always_ff @(posedge clk, negedge rst_n) begin
        if (rst_n == 0)
            q <= 0;
        else
            q <= d;
    end
endmodule
```

# Digression: Module Parameters

- Parameters allow modules to be easily changed

```
module my_flipflop(d, q, clk, rst_n);  
    parameter WIDTH=16;  
    input [WIDTH-1:0] d;  
    input clk, rst_n;  
    output logic [WIDTH-1:0] q;  
    ...  
endmodule
```

default value set to 16

- Instantiate and set parameter:

```
my_flipflop f0(d, q, clk, rst_n);
```

uses default value

```
my_flipflop #(12) f0(d, q, clk, rst_n);
```

changes parameter to 12 for this instance

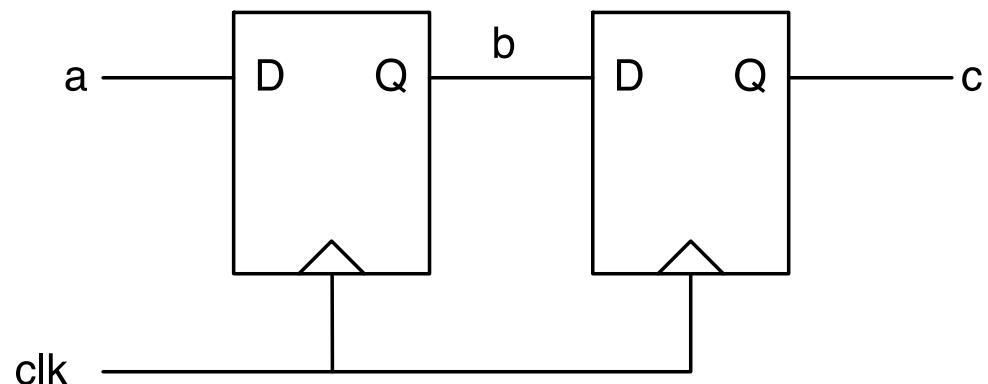
# Non-Blocking Assignment $a \leq b$ ;

- $\leq$  is the non-blocking assignment operator
  - All left-hand side values take new values concurrently

```
always_ff @(posedge clk) begin
    b <= a;
    c <= b;
end
```

c gets the **old** value of b, not value assigned just above

- This models synchronous logic!



# Non-Blocking vs. Blocking

- Use non-blocking assignment `<=` to describe edge-triggered (synchronous) assignments

```
always_ff @(posedge clk) begin
    b <= a;
    c <= b;
end
```

- Use blocking assignment `=` to describe combinational assignment

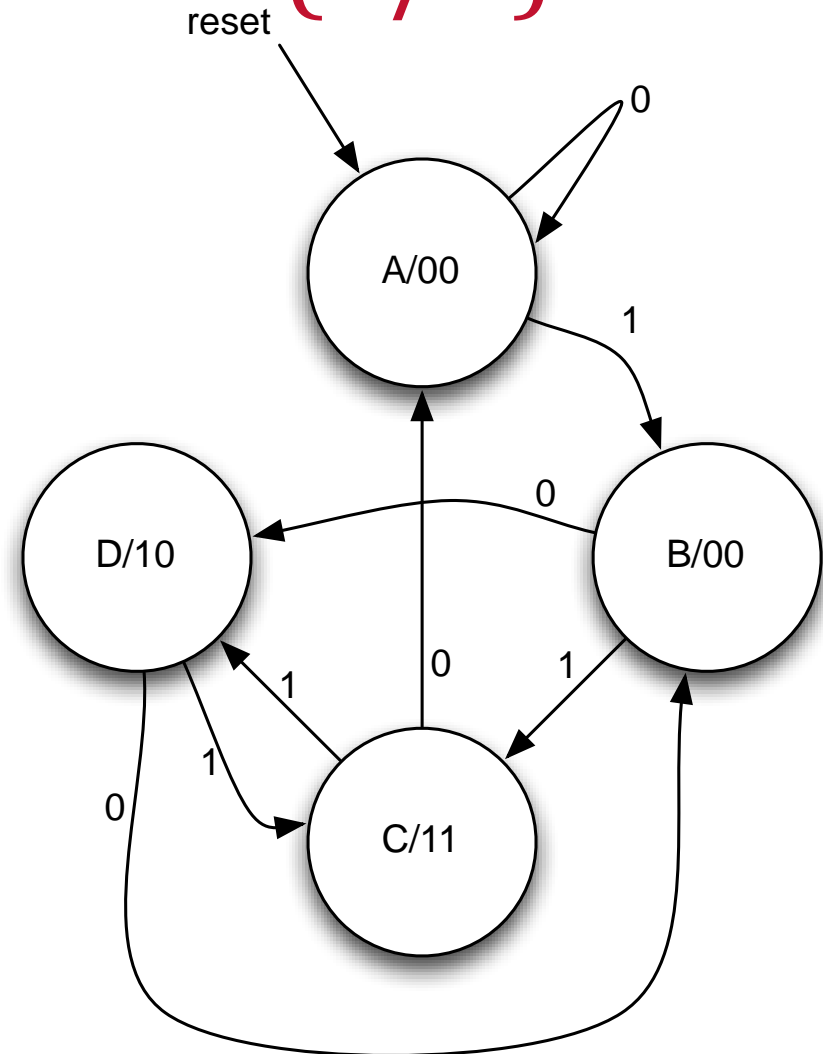
```
always_comb begin
    b = a;
    c = b;
end
```

# Design Example

- Let's say we want to compute  $f = a + b * c$ 
  - b and c are 4 bits, a is 8 bits, and f is 9 bits
- First, we will build it as a combinational circuit
- Then, we will add registers at its inputs and outputs

# Finite State Machines (1/2)

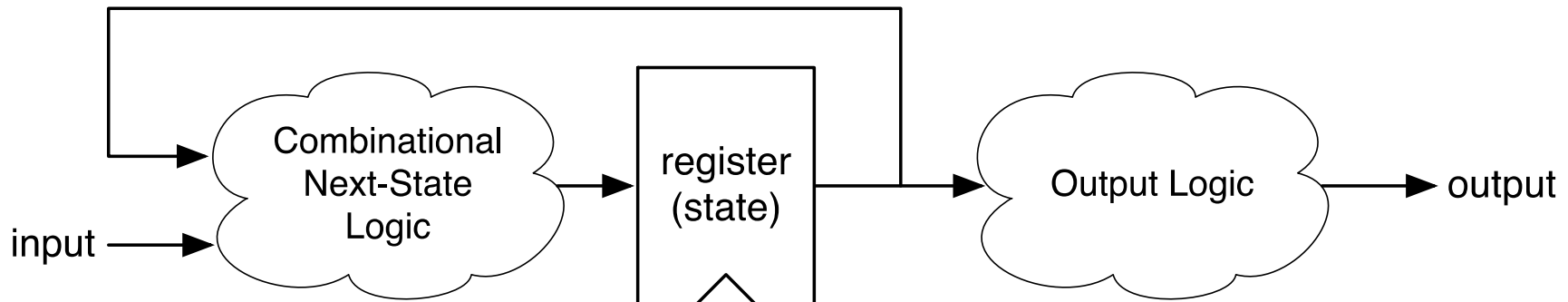
- State names
- Output values
- Transition values
- Reset state





# Finite State Machines (2/2)

- What does an FSM look like when implemented?



- Combinational logic and registers (things we already know how to do!)

# Full FSM Example (1/2)

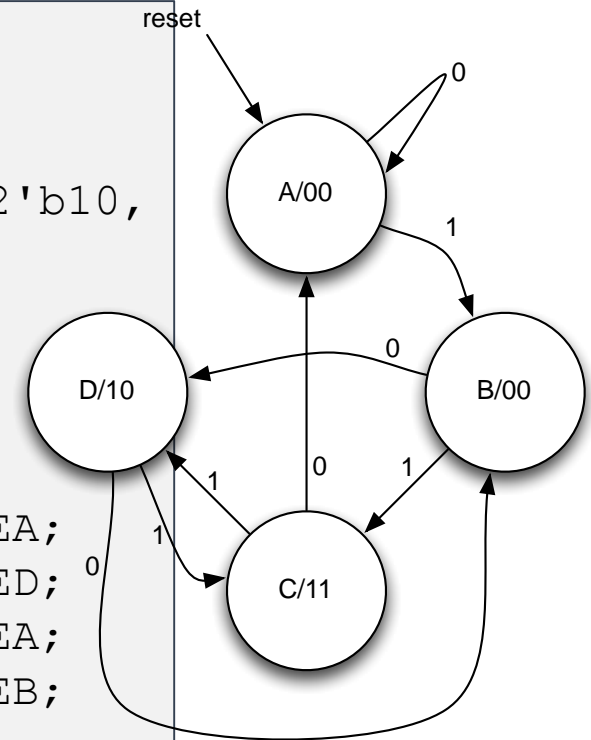
```

module fsm(clk, rst, x, y);
  input clk, rst, x;
  output logic [1:0] y;
  enum { STATEA=2'b00, STATEB=2'b01, STATEC=2'b10,
        STATED=2'b11 } state, next_state;

  // next state logic
  always_comb begin
    case(state)
      STATEA: next_state = x ? STATEB : STATEA;
      STATEB: next_state = x ? STATEC : STATED;
      STATEC: next_state = x ? STATED : STATEA;
      STATED: next_state = x ? STATEC : STATEB;
    endcase
  end

  // ... continued on next slide

```

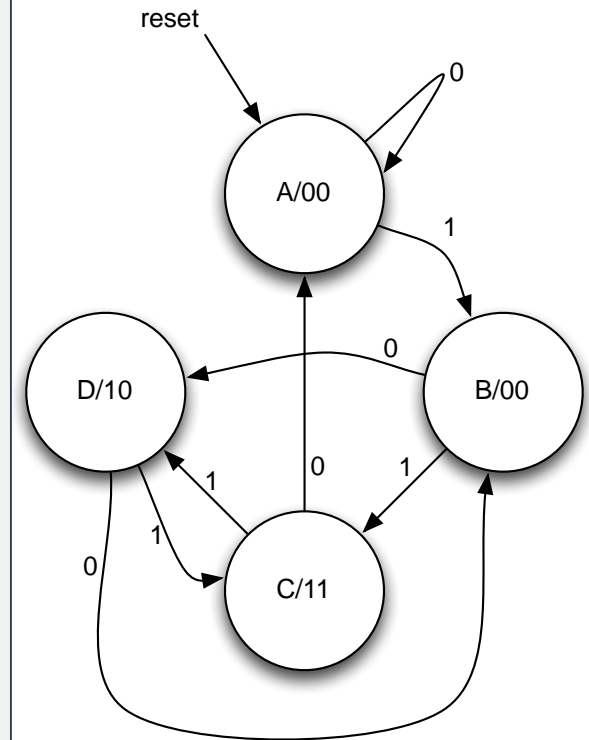


# Full FSM Example (2/2)

```

// ... continued from previous slide
// register
always_ff @(posedge clk) begin
  if (rst)
    state <= STATEA;
  else
    state <= next_state;
end
// Output logic
always_comb begin
  case(state)
    STATEA: y = 2'b00;
    STATEB: y = 2'b00;
    STATEC: y = 2'b11;
    STATED: y = 2'b10;
  endcase
end
endmodule

```



# Arrays

```
module multidimarraytest();
  logic [3:0] myarray [2:0];

  assign myarray[0] = 4'b0010;
  assign myarray[1][3:2] = 2'b01;
  assign myarray[1][1] = 1'b1;
  assign myarray[1][0] = 1'b0;
  assign myarray[2][3:0] = 4'hC;
  initial begin
    $display("myarray          == %b", myarray);
    $display("myarray[2:0]      == %b", myarray[2:0]);
    $display("myarray[1:0]          == %b", myarray[1:0]);
    $display("myarray[1]            == %b", myarray[1]);
    $display("myarray[1][2]         == %b", myarray[1][2]);
    $display("myarray[2][1:0]      == %b", myarray[2][1:0]);
  end
endmodule
```

# Memory (Combinational read)

```
module mymemory(clk, data_in, data_out,
                r_addr, w_addr, wr_en);
  parameter WIDTH=16, LOGSIZE=8;
  localparam SIZE=2**LOGSIZE;
  input  [WIDTH-1:0] data_in;
  output logic [WIDTH-1:0] data_out;
  input  clk, wr_en;
  input  [LOGSIZE-1:0] r_addr, w_addr;

  logic [WIDTH-1:0] mem [SIZE-1:0];

  assign data_out = mem[r_addr];

  always_ff @(posedge clk) begin
    if (wr_en)
      mem[w_addr] <= data_in;
  end
endmodule
```

Combinational read



Synchronous write



# Memory (Synchronous read)

```
module mymemory2(clk, data_in, data_out,
                 r_addr, w_addr, wr_en);
    parameter WIDTH=16, SIZE=256;
    localparam SIZE=2**LOGSIZE;
    input  [WIDTH-1:0] data_in;
    output logic [WIDTH-1:0] data_out;
    input  clk, wr_en;
    input  [LOGSIZE-1:0] r_addr, w_addr;

    logic [WIDTH-1:0] mem [SIZE-1:0];

    always_ff @(posedge clk) begin
        data_out <= mem[r_addr];
        if (wr_en)
            mem[w_addr] <= data_in;
    end
endmodule
```

Synchronous read

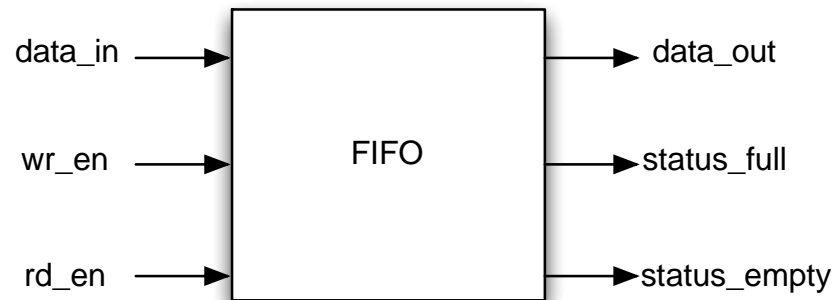
***What happens if we try to read and write the same address?***

# Assertions

- Assertions are test constructs
  - Automatically validated as design is simulated
  - Written for properties that must always be true
- Makes it easier to test designs
  - Don't have to manually check for these conditions

# Example: A Good Place for Assertions

- Imagine you have a FIFO queue
  - When queue is full, it sets `status_full` to true
  - When queue is empty, it sets `status_empty` to true



- When `status_full` is true, `wr_en` must be false
- When `status_empty` is true, `rd_en` must be false



# Assertions

- A procedural statement that checks an expression when statement is executed

Use `$display` to print text, `$error` to print error, or `$fatal` to print and halt simulation

```
// general form
assertion_name: assert(expression) pass_code;
else fail_code;

// example
always @(posedge clk) begin
    assert((status_full == 0) || (wr_en == 0))
    else $error("Tried to write to FIFO when full.");
end
```

- SV also has **Concurrent Assertions** that are continuously monitored and can express temporal conditions
  - Complex but very powerful
  - See <http://www.doulos.com/knowhow/sysverilog/tutorial/assertions/> for an introduction