

Concurrency & Synchronization

Nima Honarmand



Agenda

- Review basic concurrency concepts
 - Concurrency and parallelism
 - Data race and mutual exclusion
 - Locks
- New stuff
 - New concurrency issues: condition variables
 - How to implement locks and condition variables efficiently
 - Focusing on OS issues
 - A deeper understanding of concurrency bugs

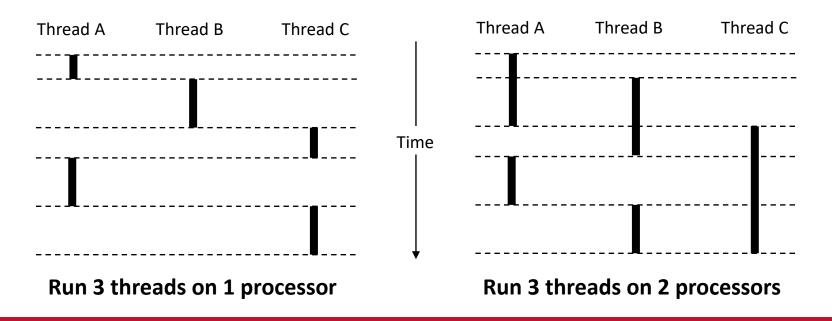


Concurrency Review



Concurrency and Parallelism

- Two tasks (threads, functions, instructions, etc.) are concurrent if their executions overlap in time
- Two tasks are parallel if they execute at the same time
 - A special case of concurrency
 - Parallel tasks have to execute on different processors





Sources of Concurrency

Question: How could one task run before the current one completes?

- 1) Tasks running on different processors
- 2) Context switching between tasks on the same processor
 - Preemptive as well as cooperative
- 3) Interrupts
 - Kernel mode: hardware interrupts and in-kernel exceptions
 - User mode: signals

Why Concurrent Programming?

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- In user-mode
 - To utilize multiple processors
 - Multi- and many-core processors are here to stay
 - To improve application responsiveness in the presence of blocking operations
 - E.g., processing a UI input in the background without freezing the application
- In kernel-mode
 - Because user-mode often requires kernel-mode concurrency
 - Each thread in a multi-threaded program has a kernel-mode component (remember the iceberg?)
 - Also, because interrupts/exceptions can create unforeseen parallelism



Challenges of Concurrency

- Crux: execution order (interleaving) of instructions of concurrent tasks in <u>not generally under our</u> <u>control</u>
 - Single CPU: We can't control scheduler decisions
 - Multi-CPU: We can't control when, and how fast, each processor executes its instructions
- We need to control instruction interleaving for at least two reasons
 - 1) Mutual exclusion
 - 2) Condition synchronization



Mutual Exclusion

- Some computer resources cannot be accessed by multiple threads at the same time
 - E.g., a printer can't print two documents at once
- **Mutual exclusion** is the term to indicate that some resource can only be used by one thread at a time
 - Active thread excludes its peers
- In concurrent programs, shared data structures are often mutually exclusive
 - Two threads adding to a linked list at the same time can corrupt the list



Why Mutual Exclusion for Shared Data?

- To avoid data races
- Imagine two concurrent threads executing this code
- What is your expected outcome?
- What are the possible outcomes?
- Undesirable things happen when concurrent tasks access shared data simultaneously
 - At lease one access should be a write for bad things to happen

C code:		
balance	+=	1;

Assembly code: mov 0x8049a1c, %eax add \$0x1, %eax mov %eax, 0x8049a1c



Why Mutual Exclusion for Shared Data?

- As programmers, we are used to thinking sequentially
 - We break a functionality into a sequence of code lines or instructions
 - → We almost always use more than one instruction/line of code to achieve our goal
- We are also used to think only about the results of the current piece of code
 - Difficult for us to think about the effect of a concurrent task monkeying around with the data we are using
- Is this human nature or just because of how we were taught programming?
 - The jury is out on this!



Why Mutual Exclusion for Shared Data?

• To recap

- 1) We have to do multiple things to implement an operation
 - Either do all of it, or none of it
 - Partial execution will result in an inconsistent state
- We don't want anyone to touch the data we are using when doing that
 - We need isolation from others
- So, we need *atomicity*
 - Do either all or none + in isolation



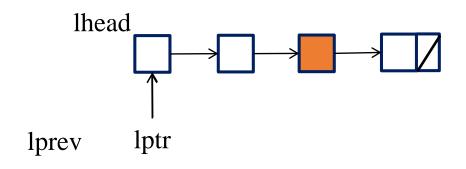
Why Mutual Exclusion for Shared Data?

- One way to (almost) achieve atomicity is...
- ...to make sure we have *exclusive* access to our shared data for the length of time our *critical* instructions run
 - Hence, the name "mutual exclusion"
- A critical section of code is any piece of code that touches shared data (or more generally, accesses a shared resources)
 - It's an abstraction to help us think more clearly about structure of concurrent code
- Locks are our main mechanisms to achieve mutual exclusion



Example: Traverse a Linked List

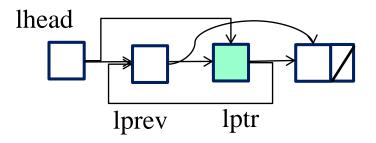
- Suppose we want to find an element in a singly linked list, and move it to the head
- Visual intuition:





Example: Traverse a Linked List

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- Visual intuition:





Example: Traverse a Linked List

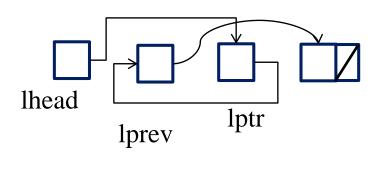
```
lprev = NULL;
for(lptr = lhead; lptr; lptr = lptr->next) {
   if(lptr->val == target){
       // Already head?, break
       if(lprev == NULL) break;
       // Move cell to head
       lprev->next = lptr->next;
       lptr->next = lhead;
       lhead = lptr;
      break;
   lprev = lptr;
}
```

• Where is the critical section?



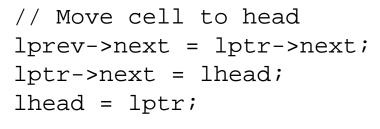
Thread 1

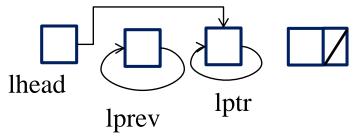
// Move cell to head
lprev->next = lptr->next;
lptr->next = lhead;
lhead = lptr;



Thread 2

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- A critical section often needs to be larger than it first appears
 - The 3 key lines are not enough of a critical section



Thread 1

```
lprev = NULL;
for(lptr = lhead; lptr; lptr = lptr->next)
{
    if(lptr->val == target){
        // Already head?, break
        if(lprev == NULL) break;
        // Move cell to head
        lprev->next = lptr->next;
        lptr->next = lhead;
        lhead = lptr;
        break;
    }
    lprev = lptr; }
```

- Putting entire search in a critical section reduces concurrency, but it is safe
- Writing high-performance and correct concurrent programs is a (very) difficult task

```
lprev = NULL;
for(lptr = lhead; lptr; lptr = lptr-
>next) {
    if(lptr->val == target){
        // Already head?, break
        if(lprev == NULL) break;
        // Move cell to head
        ...
```

Thread 2

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Condition Synchronization

- Mutual exclusion is not all we need for concurrent programming
- Very often, synchronization consists of one task waiting for another to make a condition true
 - Ex1: master thread tells worker thread a request has arrived
 - Worker thread has to wait until this happen
 - Ex2: parent thread waits until a child thread terminates (pthread_join())
- Until condition becomes true, thread can sleep
 - Ties synchronization to scheduling
- We use **condition variables** for this purpose (next lecture)